

# Trustworthy Autonomous Systems

## RS-2C Securing the Communication Surface



Engineering and Physical Sciences Research Council



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### Introduction

Communications of autonomous systems are vulnerable to attacks and eavesdropping, due to

- broadcasting communication nature
- the lack of randomness of the line-of-sight (LoS) dominated communication channels

### Contents

1. What is Physical Layer Secret Key Generation (PL-SKG)
2. A cooperative and multiple Eavesdropper Threat
3. Random-Matrix based PL-SKG

### Key-less PLS vs PL-SKG

#### Key-less physical layer security (key-less PLS):

maximize secrecy rate or signal-to-interference-noise-ratio (SINR), by optimizing trajectory, beamforming, IRS phase.

**Advantage:** key-less, easy deployment

**Disadvantage:** no solution guarantee when combined with mission & control layers objectives & constraints

#### Physical Layer Secret Key Generation (PL-SKG):

Generate shared secret key via the reciprocal small-scale channel randomness.

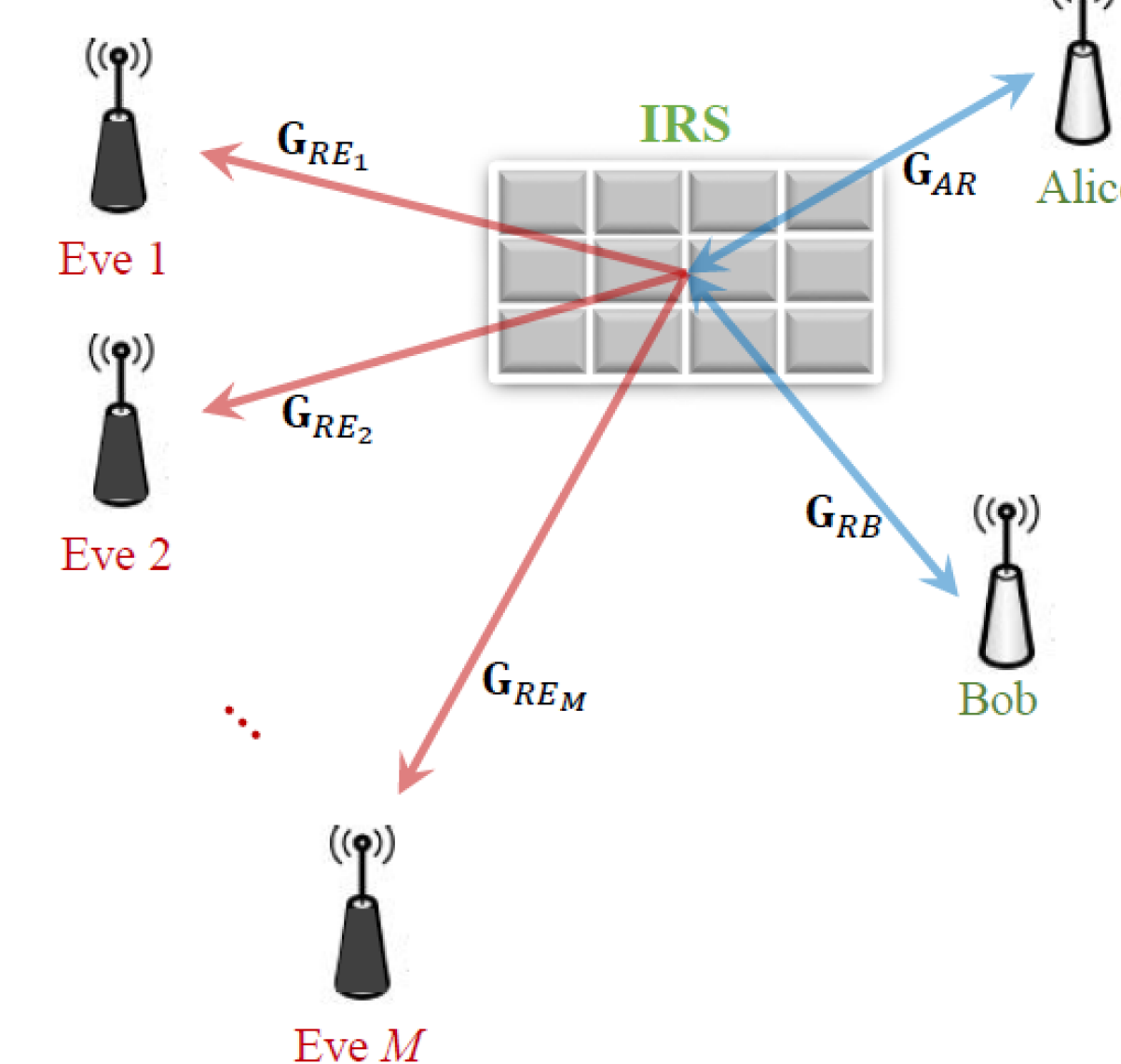
**Advantages:** detached from mission & control layer optimization

**Disadvantages:** requires sufficient small-scale scattering & randomness

## 2. A Cooperative Eavesdropping Threat

Intelligent reflecting surface (IRS) is a promising technology to secure the LoS dominated low-entropy channels, by:

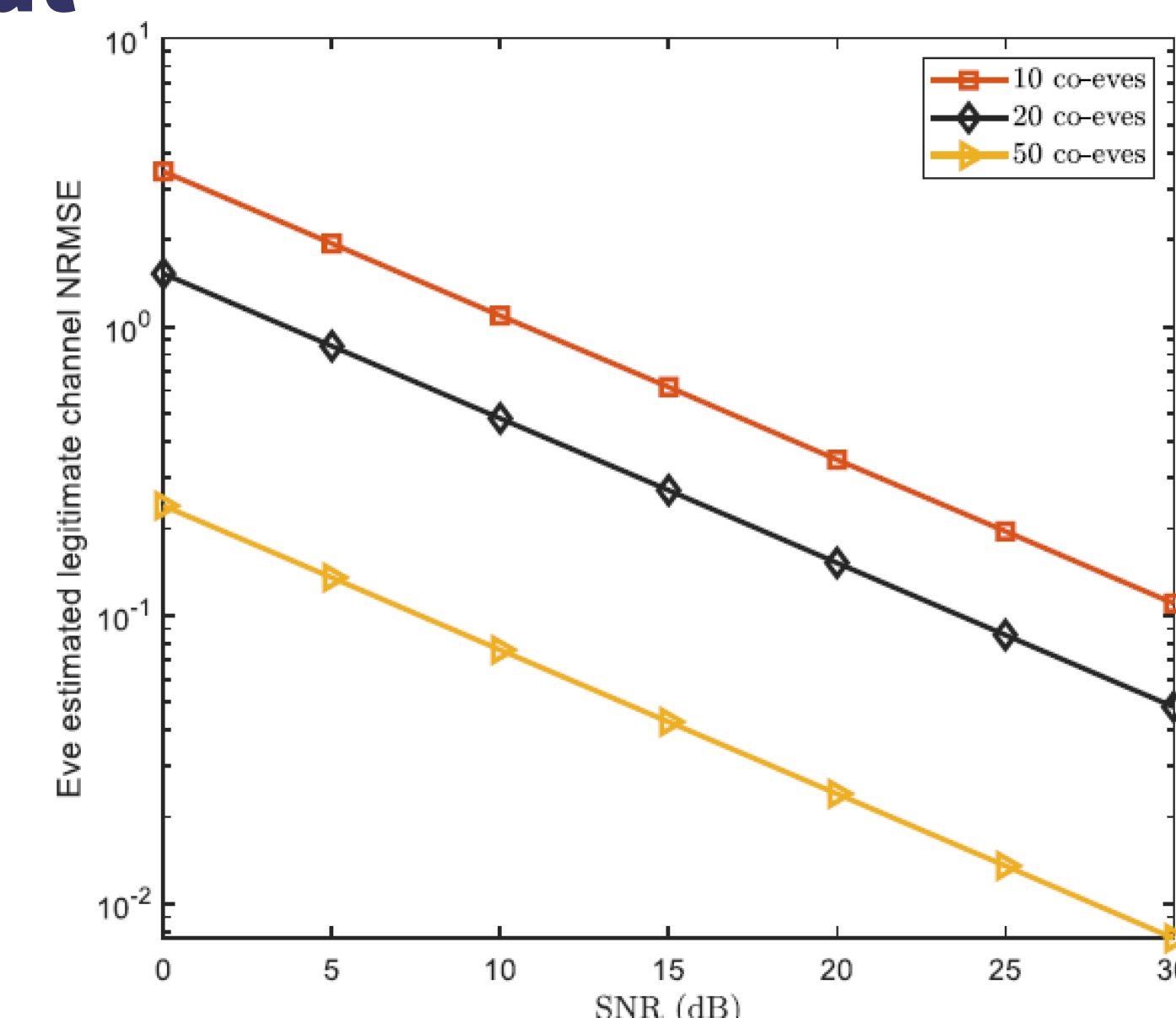
- Induce randomness via IRS phases
- Extra space for beamforming
- Artificial noise for anti-jamming



However, the IRS-induced randomness is also contained in the Eves' received signals, which enables the estimation of the legitimate channel by multiple & cooperative Eves.

### Theory behind Multi-Eve Threat

The deployment of  $N$  Eves is to ensure the mutual information between  $N$  Eves' received signals and the legitimate channel equal the information entropy of the latter, which suggests a successful estimation of the legitimate channel from Eves.

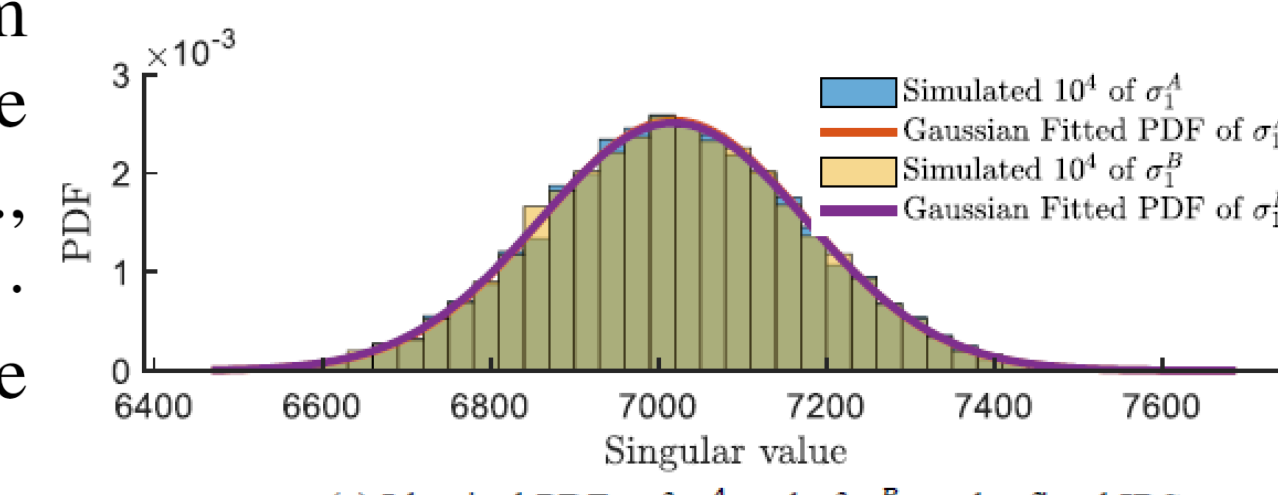


## 3. Random-Matrix based PL-SKG

Recalling from the Multi-Eve design that the prerequisite of channel estimation by Eves is the known of pilot sequences  $\mathbf{u}_A, \mathbf{u}_B$ . This inspires us to use random matrices instead of the public known pilot sequences. And this is random-matrix based PL-SKG.

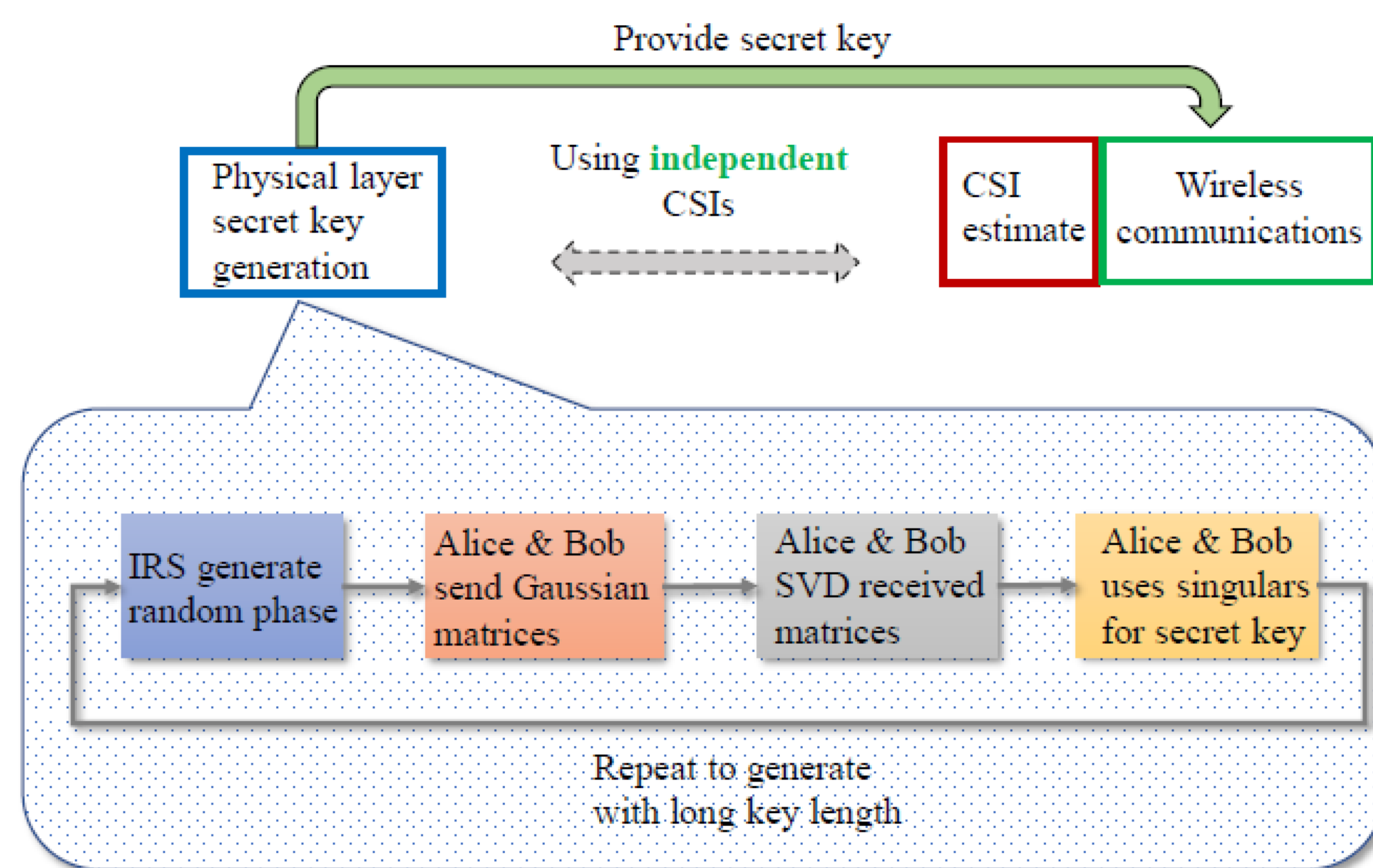
### Theory of Random-Matrix based PL-SKG

**Theorem 1:** Consider a matrix  $\mathbf{H} \in \mathbb{C}^{N \times L}$ , and two random matrices  $\mathbf{X}_1 \in \mathbb{C}^{N \times D}$  and  $\mathbf{X}_2 \in \mathbb{C}^{L \times D}$ , where elements are i.i.d and follow the normal complex Gaussian distribution, i.e.,  $\mathcal{CN}(0, 1)$ . Then, the singular values of  $\mathbf{H} \cdot \mathbf{X}_1$  and of  $\mathbf{H}^H \cdot \mathbf{X}_2$ , denoted as  $\sigma(\mathbf{H}\mathbf{X}_1)$  and  $\sigma(\mathbf{H}^H\mathbf{X}_2)$ , follow the same probability distribution.

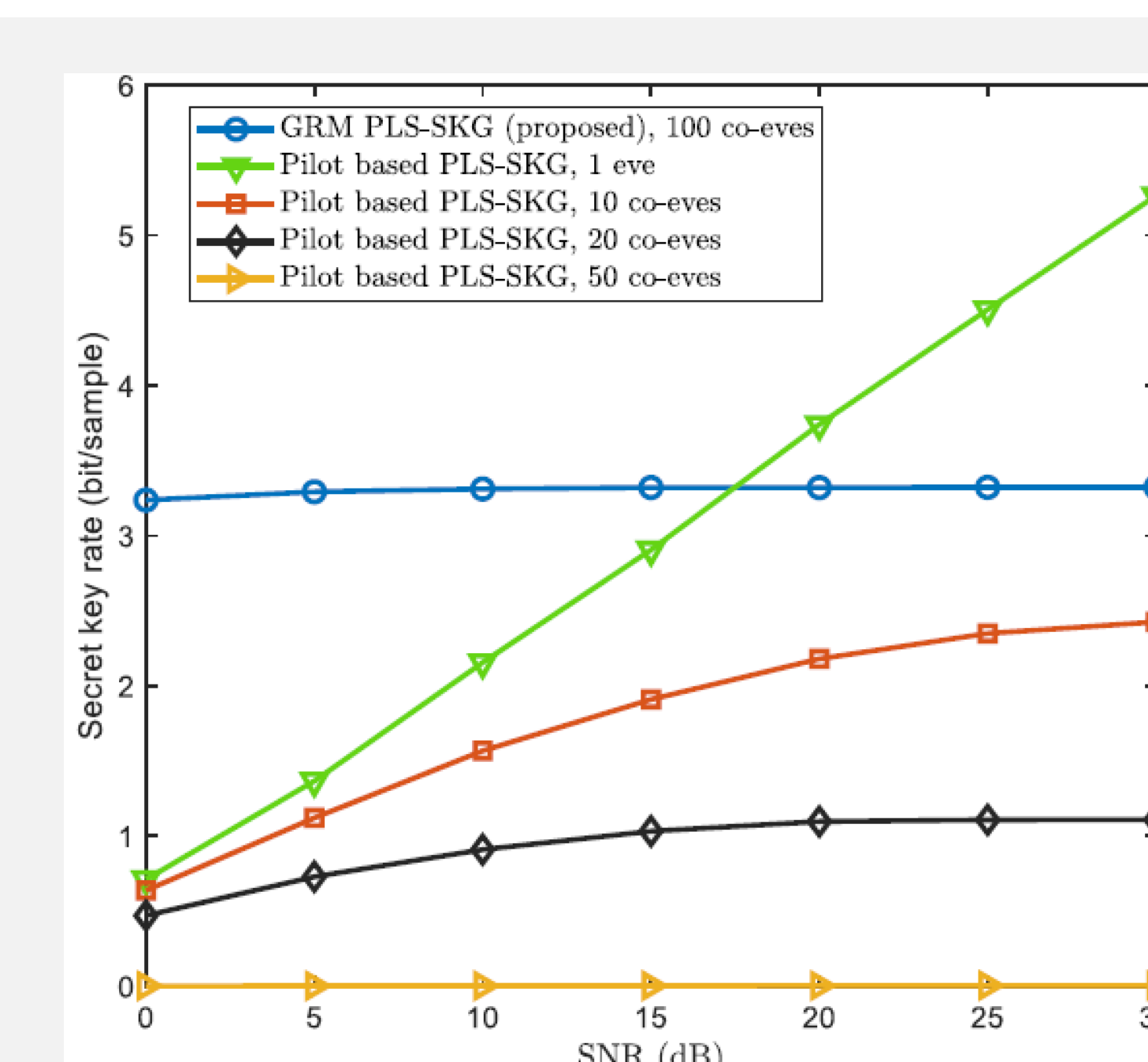


(a) Identical PDFs of  $\sigma_A^2$  and of  $\sigma_B^2$ , under fixed IRS  $\mathbf{w}$

### Sketch of Random-Matrix based PL-SKG



### Results



The result shows our proposed random matrix based PL-SKG:

- comparatively superior (up to 300%) secret key rate in low SNR regime, attributed to the noise resistance ability of the singular values
- generally improved secret key rate performance against Multi-Eves.

## 1. Secret Key Generation in IRS-aided LoS Channel

PL-SKG exploits the channel randomness & reciprocity between legitimate Alice and Bob. The vital step for PL-SKG is how to derive the reciprocal & random legitimate channel between Alice and Bob. Such channel probing results serve as the seed for further key generation.

### How to derive common channel property

**Step 1:** IRS generate an independent IRS phase  $\mathbf{w}$  for each channel estimation round.

**Step 2:** Alice and Bob send pilots  $\mathbf{u}_A$  and  $\mathbf{u}_B$  to each other in TDD mode. Alice's and Bob's received signals are:

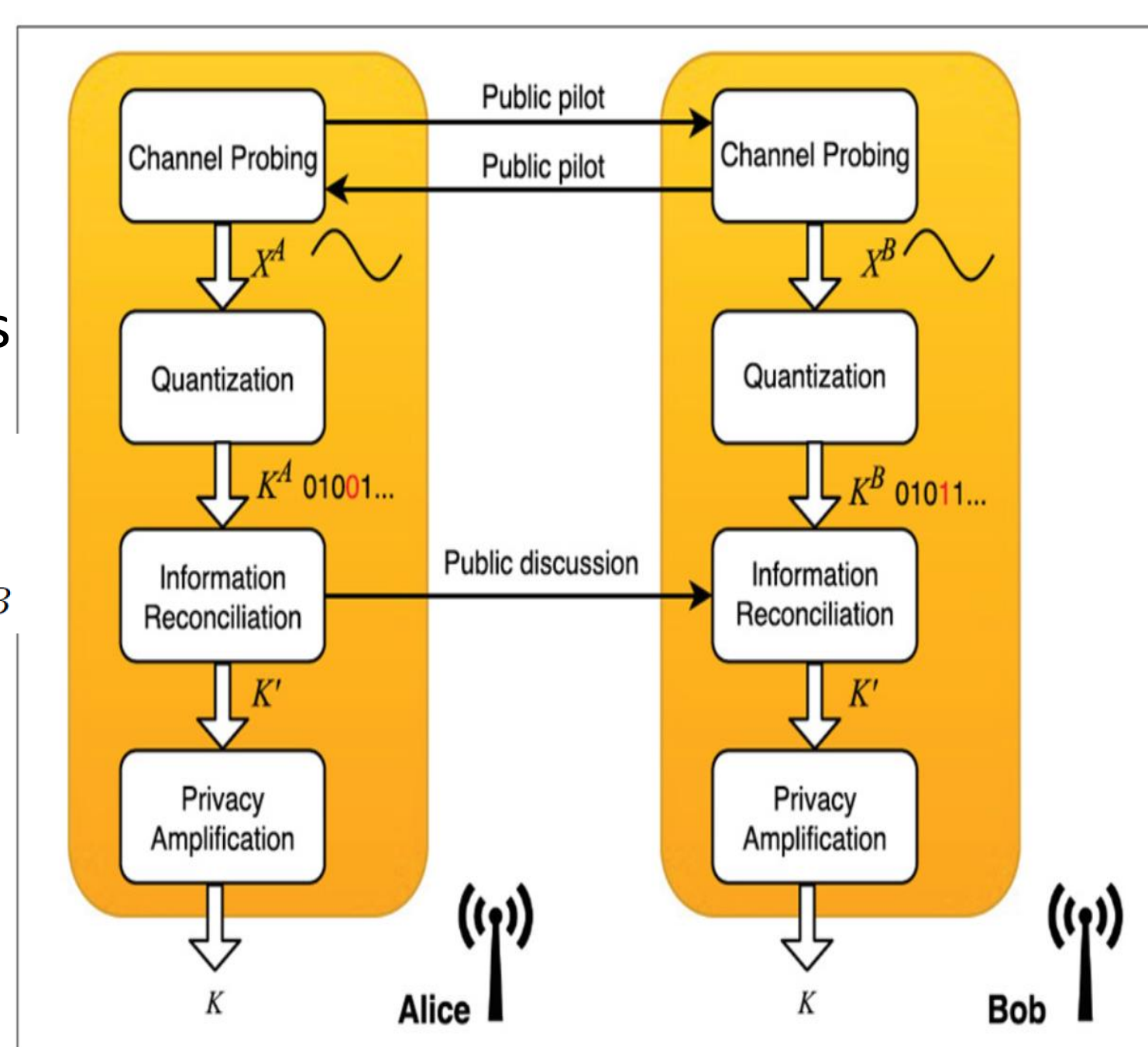
$$\mathbf{y}_A = (\mathbf{h}_{BA} + \mathbf{h}_{RA} \cdot \text{diag}(\mathbf{w}) \cdot \mathbf{h}_{BR}) \cdot \mathbf{u}_B + \epsilon_A$$

$$\mathbf{y}_B = (\mathbf{h}_{AB} + \mathbf{h}_{RB} \cdot \text{diag}(\mathbf{w})^H \cdot \mathbf{h}_{AR}) \cdot \mathbf{u}_A + \epsilon_B$$

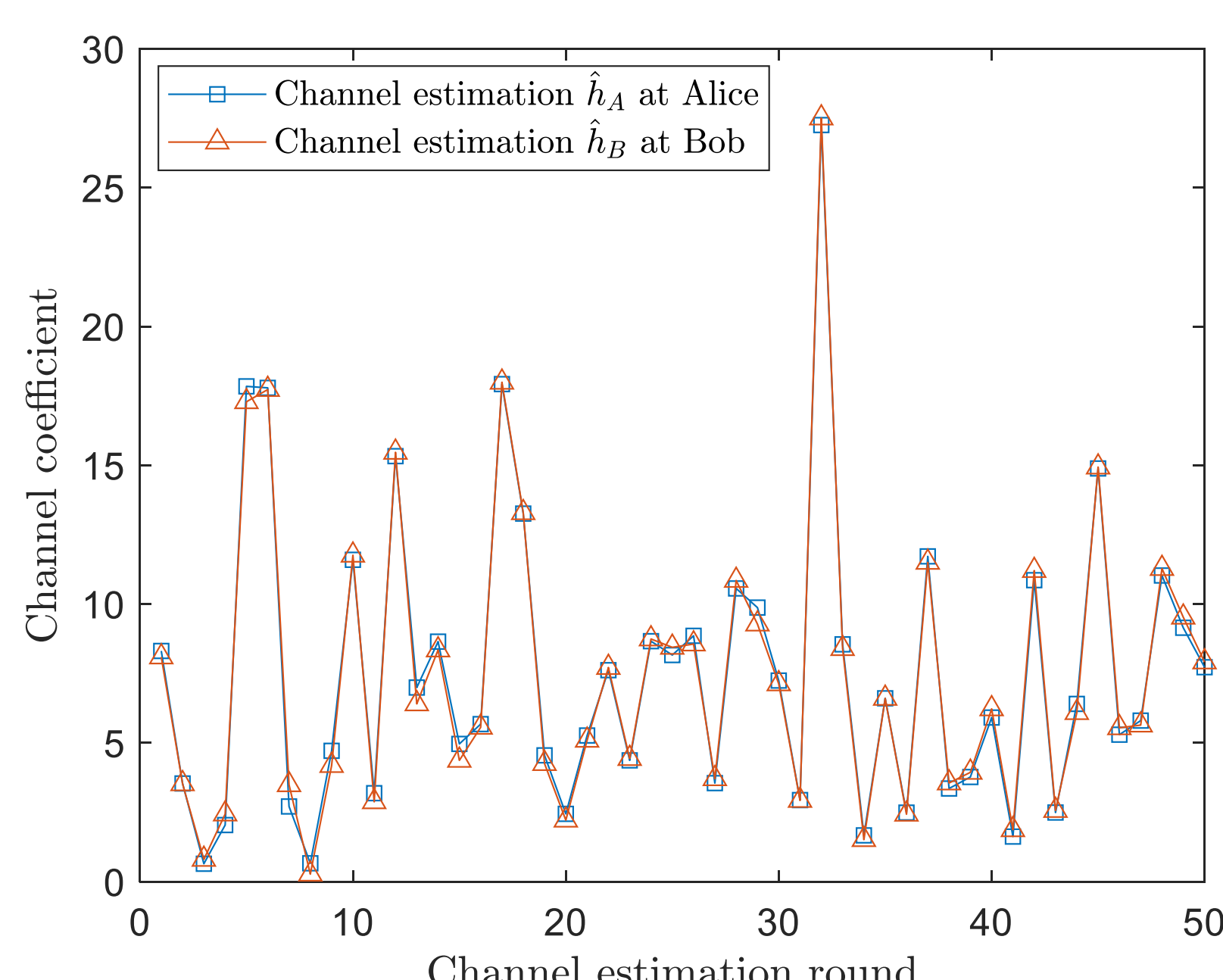
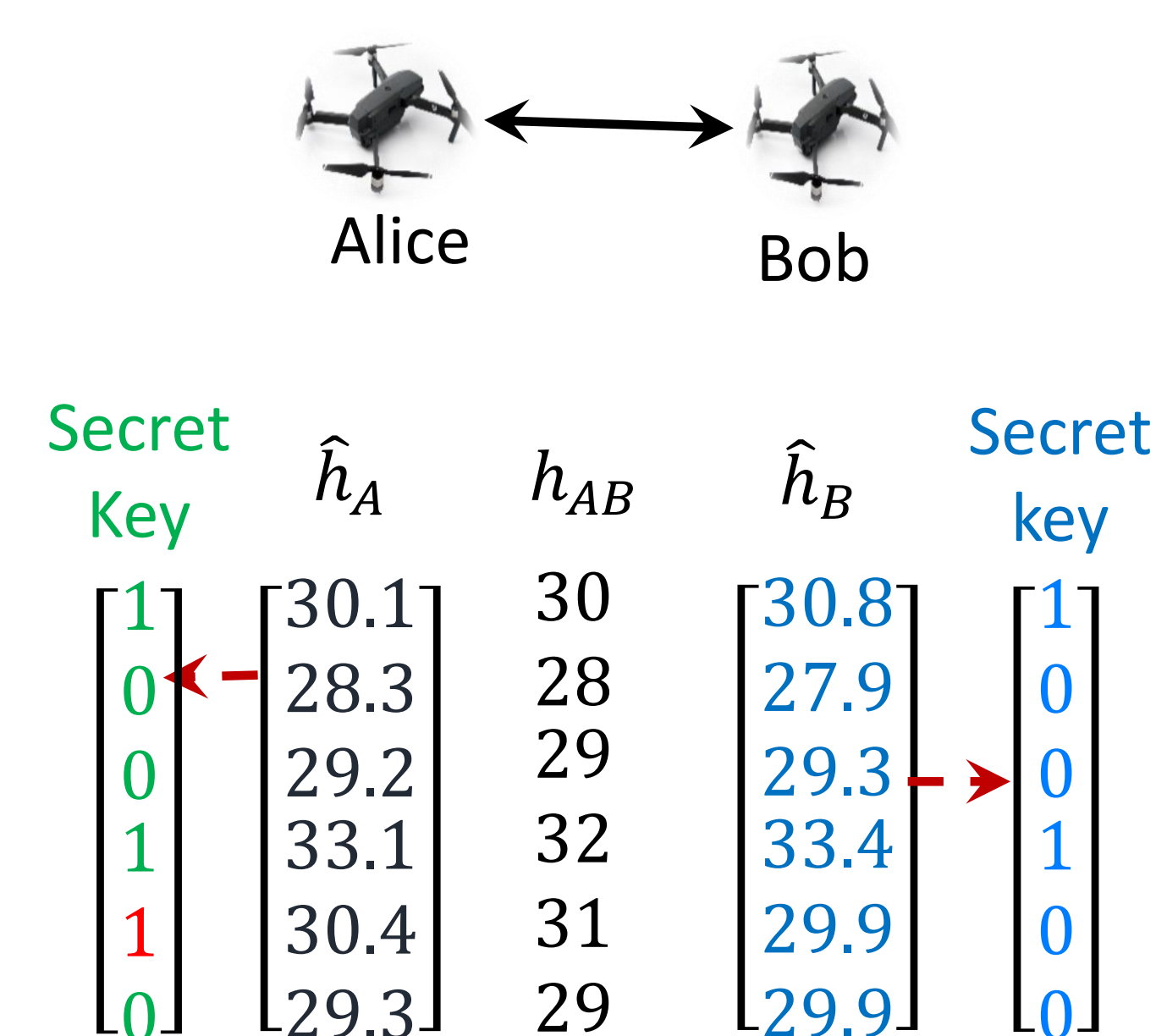
**Step 3:** Alice and Bob estimate the channel via the received signals, i.e.,

$$\hat{\mathbf{h}}_A = \frac{\mathbf{u}_B^H \mathbf{y}_A}{\|\mathbf{u}_B\|_2} = (\mathbf{h}_{BA} + \mathbf{h}_{RA} \cdot \text{diag}(\mathbf{w}) \cdot \mathbf{h}_{BR}) + \hat{\epsilon}_A$$

$$\hat{\mathbf{h}}_B = \frac{\mathbf{u}_A^H \mathbf{y}_B}{\|\mathbf{u}_A\|_2} = (\mathbf{h}_{AB} + \mathbf{h}_{RB} \cdot \text{diag}(\mathbf{w})^H \cdot \mathbf{h}_{AR}) + \hat{\epsilon}_B$$



### Example



This work is supported, in part, by the Engineering and Physical Sciences Research Council [grant number: EP/V026763/1]