

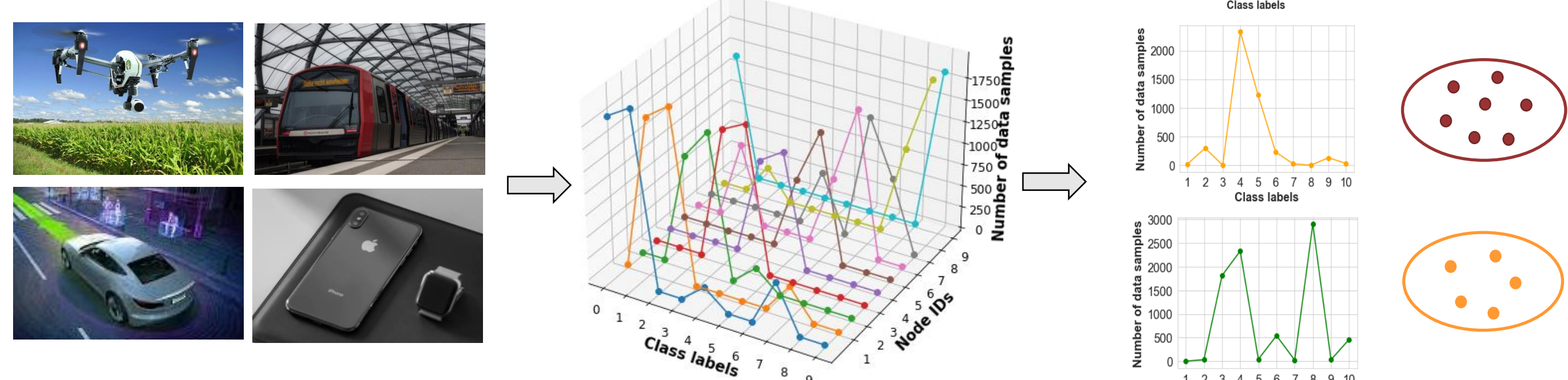
Machine Learning Frameworks for Autonomous System

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Heterogenous Data in Autonomous System (AS)

- Distributed nodes in AS contain varied data distribution
- Centralized Machine Learning (ML) frameworks:
 - Reduce model accuracy
 - Privacy risk
 - Increase communication cost

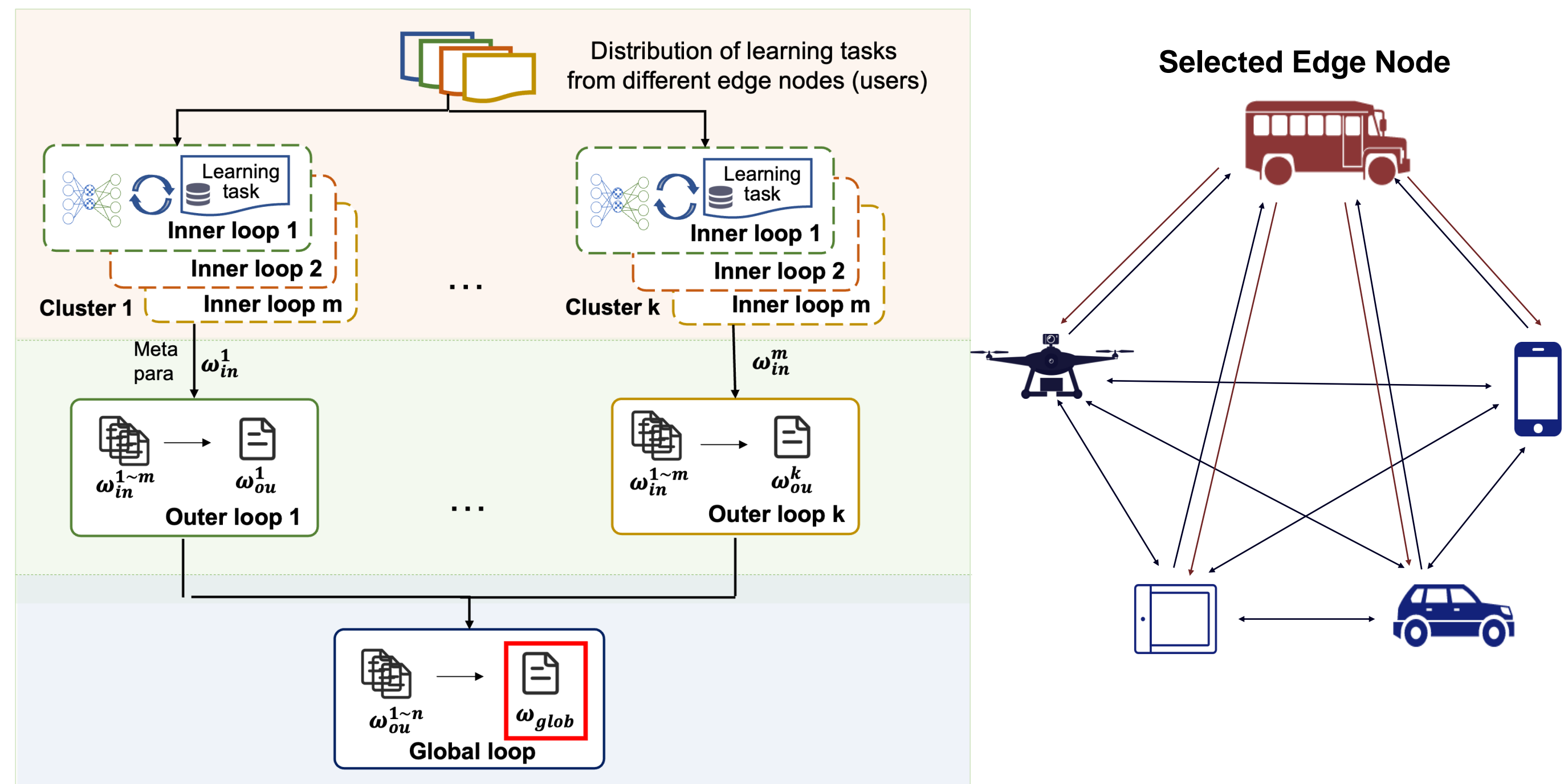


Adaptive and Hierarchical Peer-to-Peer Federated Meta-Learning Framework

Develop a **hierarchal federated meta-learning** framework to adaptively match the characteristics of heterogeneous data (PPFM)

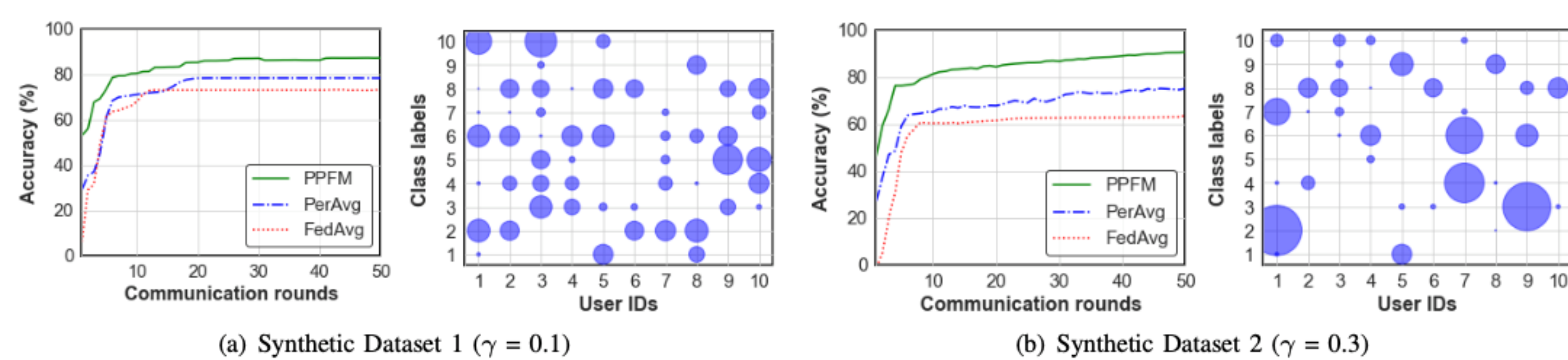
Contributions:

- A novel hierarchal meta-learning architecture
 - Generate multiple learning loops to match different data distribution
- A peer-to-peer federated learning approach
 - Ease reliance on the fixed central server
- A federated learning based data clustering method



Experimental results:

PPFM improves accuracy and efficiency over the state-of-art approaches

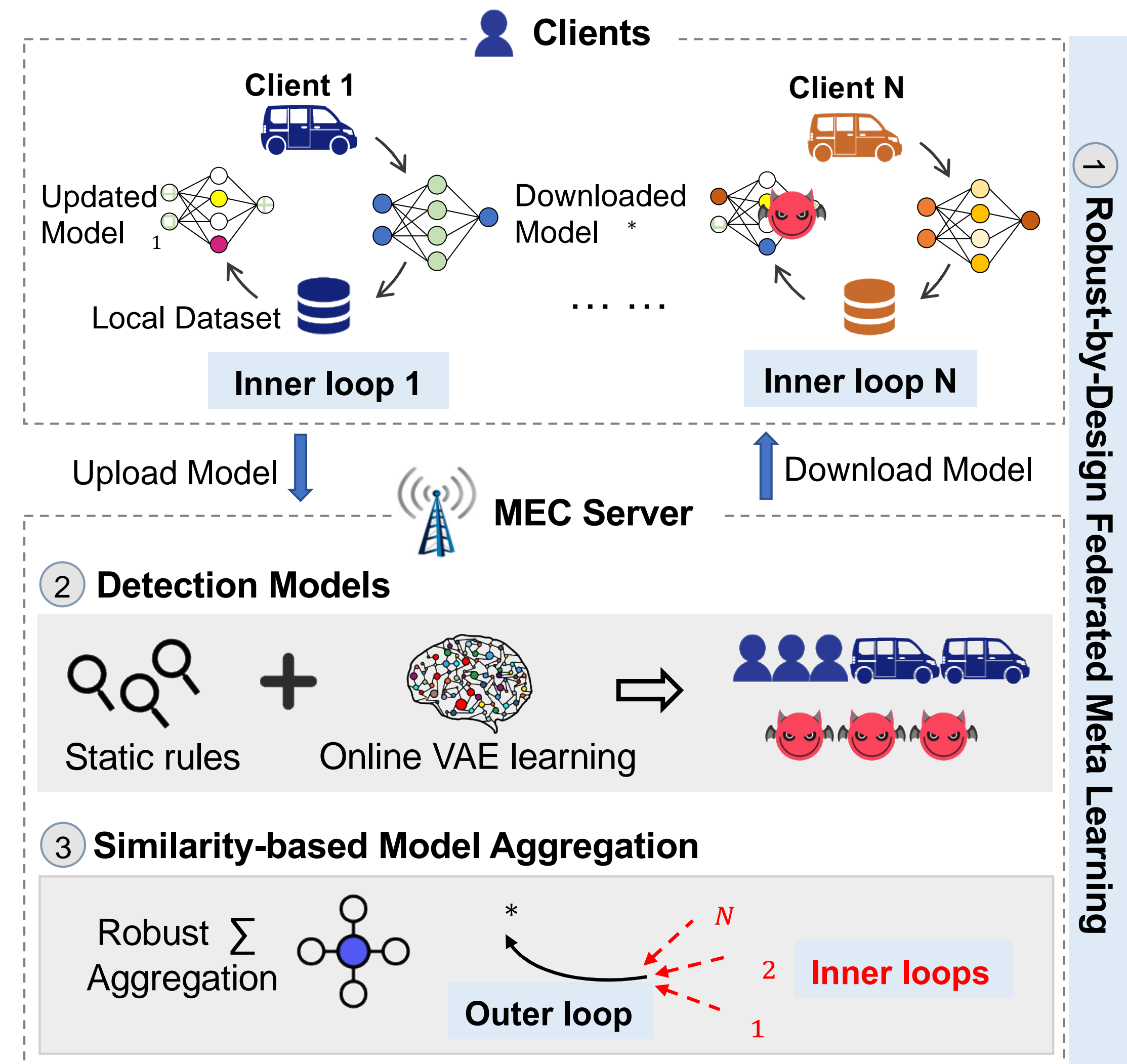


Robust Federated Meta Learning Framework

Develop a **robust and adaptive** federated meta-learning framework against adversaries (RAFL)

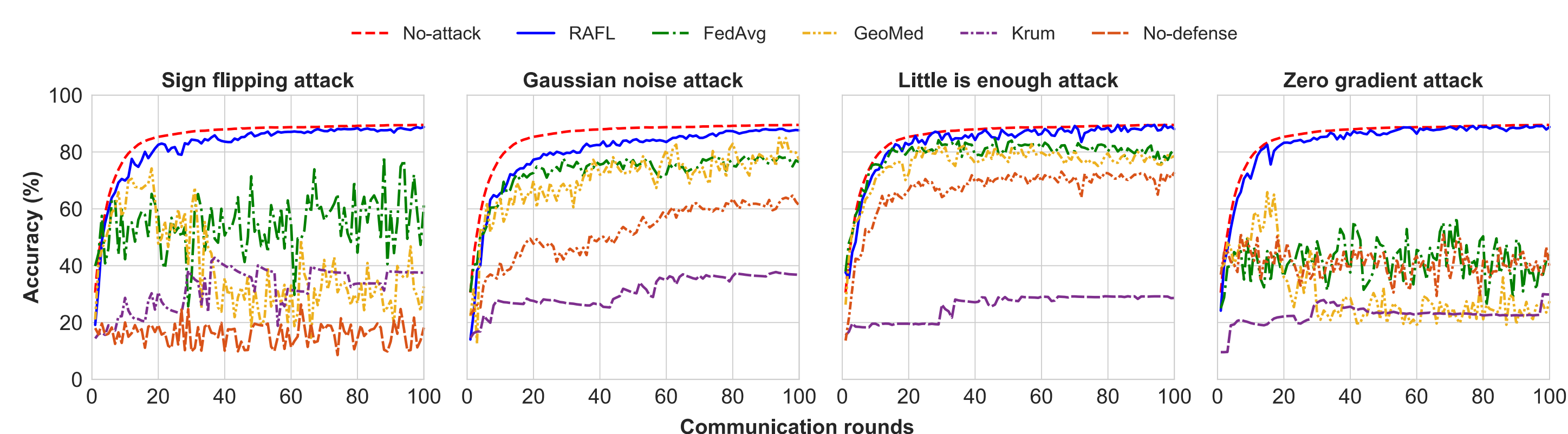
Contributions:

- A robust-by-design federated meta-learning architecture
 - Adaptively defend against a range of adversarial attacks.
- A composite rule-based and learning-based detection method
 - Identify adversaries via ranking domain and low-dimensional embeddings.
- An adaptive model aggregation method
 - Aggregate the global model by considering the degree of similarity between the meta-model and calculated mean model to resilience attacks.



Experimental results:

RAFL is robust by design and outperforms other baseline defensive methods against adversaries in terms of model accuracy and efficiency

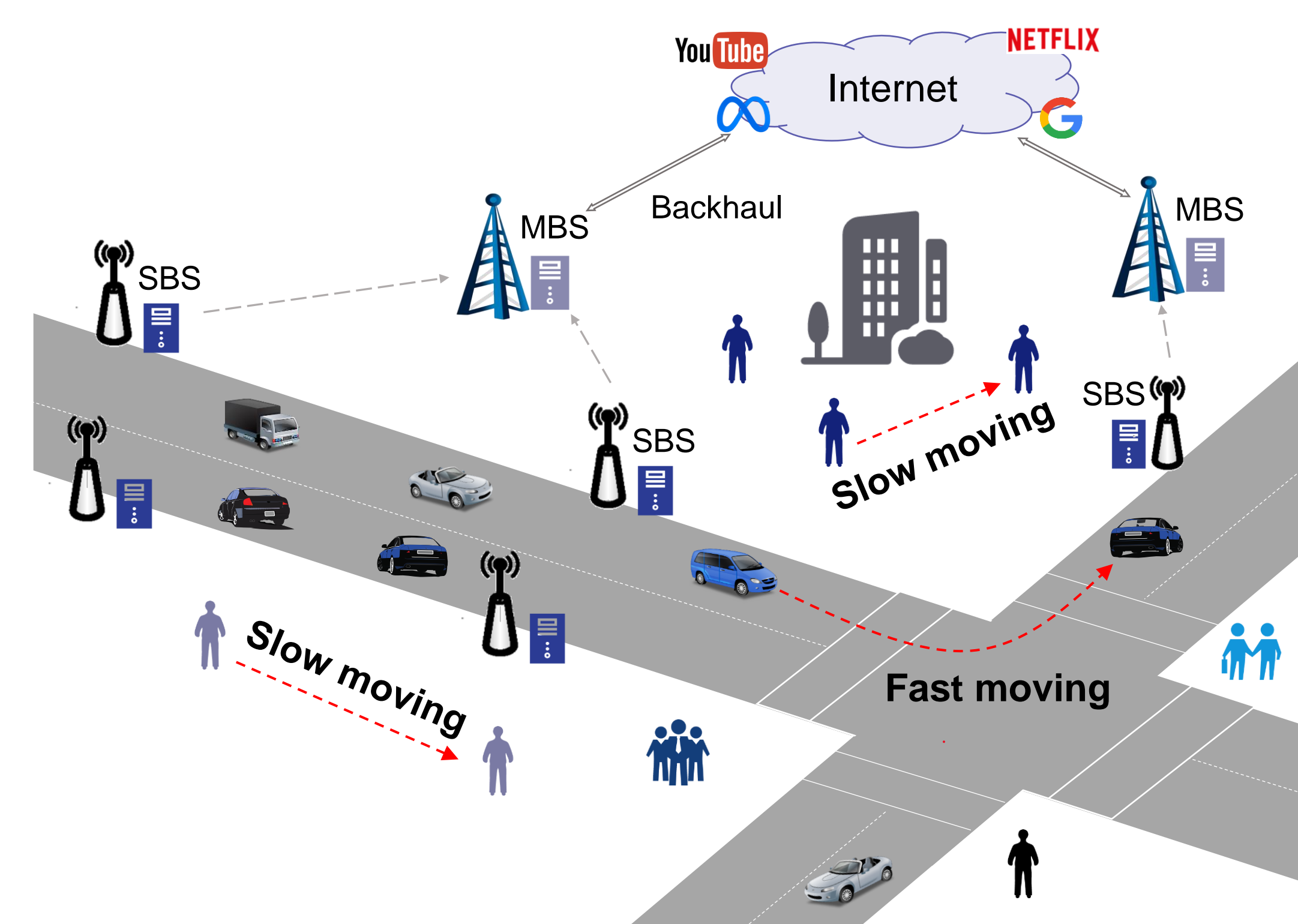


Mobility-aware Federated Learning Framework

Develop a **mobility-aware federated meta-learning** framework to reduce the impact of node mobility

Contributions:

- A novel federated split learning architecture
 - Address the fast changing data distribution
- A semantic-based clustering approach
 - Quick assign edge nodes with non-IID dataset into different distribution



Case Study: Federated Meta Reinforcement Learning for UAV Navigation

Federated Learning-based Visual Odometry Framework

- Combining the AI-based solutions with classical filter-based approach
- Utilising RAFL framework to improve pose estimation accuracy
- Aggregating models trained in different environments and conditions

